

LIVORNO (IT)

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Overview of the Italian PS



Specific features:

- The testbed encompasses the area of the **Port of Livorno** and the **Florence** - Livorno highway.
- IoT devices are deployed in the car and along the roads in both the **Highway** and the **Urban Area**.
- 7 JEEP Renegade prototype vehicles are used: 2 connected and AD cars, 5 connected cars.
- A **connected bicycle prototype** is also included in the loop.
- The MONI.C.A.TM Port Monitoring Centre, Traffic Control Centre with **DATEX-II** node are integrated into the PS ICT infrastructure.

Use cases:



- Highway Pilot: road hazard events announced by IoT devices enable speed adaptation and lane change functions on the AD cars.



- Urban driving: vulnerable road user are detected at traffic light intersection and trigger brakes on the AD cars.

Partners involved:



















MONI.C.A.





Supported by:

Use Cases - Highway

Scenario:

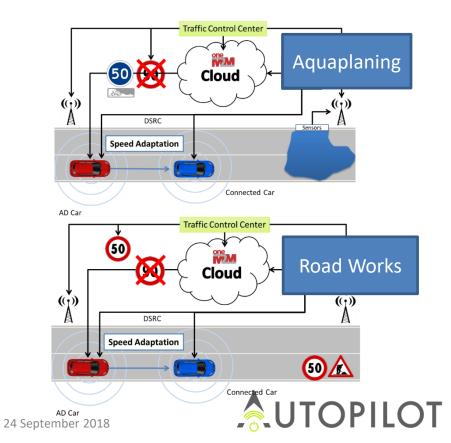
Livorno- Florence public highway

Target:

 Avoiding accidents in a real-world dense environment featuring 40,000 vehicles / day (heavy trucks 20%)

Tackling with:

- common events:
 - road works (poorly flagged in case of urgent works)
- specific events:
 - rain water standings (Tuscany is rainy in autumn/spring)





Use Cases - Urban

Scenario:

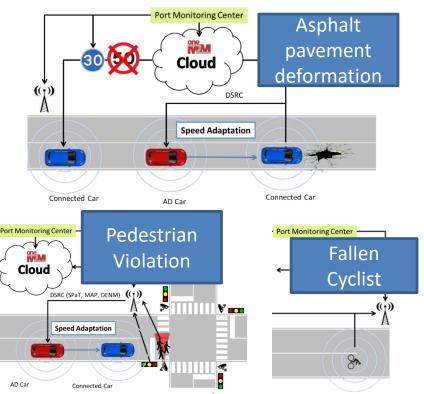
Port of Livorno maritime terminal

Target:

 Avoiding accidents in a the embarkment area of the cruise and ferry terminals (2 million passengers / year)

Tackling with:

- urban-like typical events:
 - pedestrian traffic light violation
 - fallen cyclist in the intersection
 - pavement deformation







IoT components of the Italian PS •



Devices

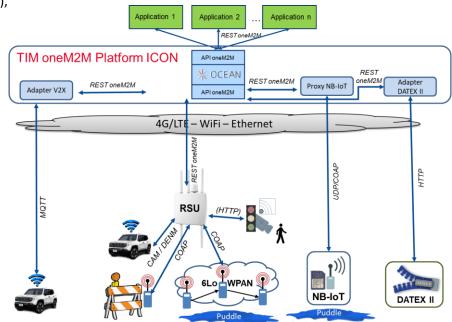
- Puddle IoT sensors (based on 6LowPAN and NB-IoT technologies),
- Pothole detector,
- Smart Trailer (announcing roadway works),
- Road Side Units.
- On Board Units (cars and bicycle),
- Smart traffic light,
- Smart camera.

Networks

- Port Wireless Backcone.
- Highway Backbone (Tuscan Institutional Cabled Network),
- ETSI G5.
- NB-IoT/6LoWPAN,

Platforms

- Infrastructure OneM2M platform,
- In-vehicle IoT platform.







DENM validation interface



The DENM interface will be used by AVR TCC to geolocalize and validate events exchanged between the devices and the cloud platform





IoT final user services







Enabling:

 Port Monitoring by IoT functions for drivers and VRU safety



Validating:

 IoT detections as (DATEX formatted) events flowing through TCC





Thank you



